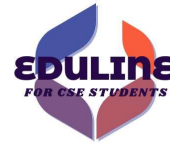


MODULE 4

PUSH DOWN AUTOMATA (PDA)



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PUSH DOWN AUTOMATA (PDA)

- Pushdown automata is a way to implement a CFG in the same way we design Finite Automata (FA) for a regular grammar.
- A FA can remember a finite amount of information, but a PDA can remember an infinite amount of information.

Pushdown automata = "Finite State Machine + stack memory"

- The addition of stack is used to provide a last-in-first-out memory management capability to Pushdown automata.
- Pushdown automata can store an unbounded amount of information on the stack.

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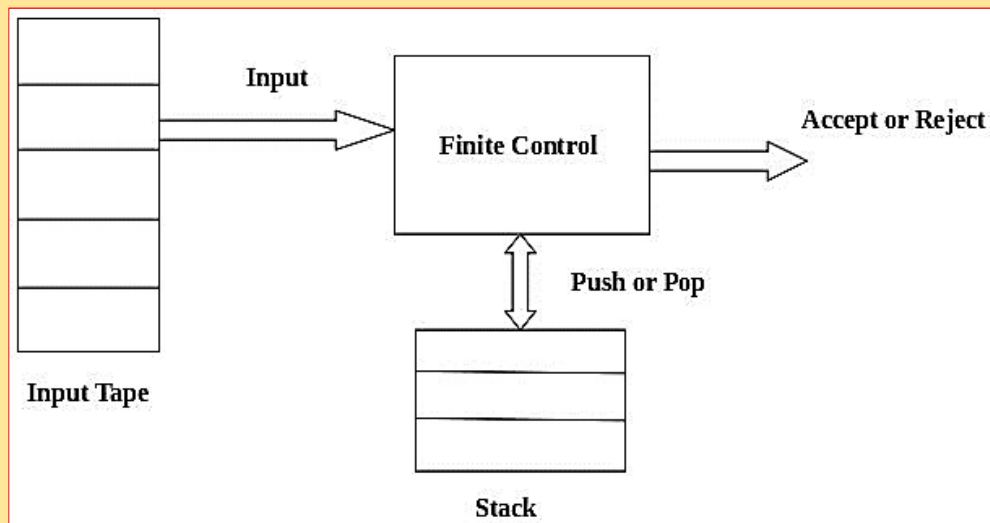
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- PDA is more powerful than FSM (Finite State Machine)
- A PDA can push an element onto the top of the stack and pop off an element from the top of the stack.
- To read an element into the stack, the top elements must be popped off and are lost.
- A PDA is more powerful than FA.
- Any language which can be acceptable by FA can also be acceptable by PDA.
- PDA also accepts a class of language which even cannot be accepted by FA. Thus PDA is much more superior to FA.

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Fig: Push Down Automata (PDA)



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❖ PDA Components

- **Input tape:** The input tape is divided in many cells or symbols. The input head is read-only and may only move from left to right, one symbol at a time.
- **Finite control:** The finite control has some pointer which points the current symbol which is to be read.
- **Stack:** The stack is a structure in which we can push and remove the items from one end only.
 - It has an infinite size.
 - In PDA, the stack is used to store the items temporarily.

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❖ Formal definition of PDA

The PDA can be defined as a collection of 7 components:

Q : the finite set of states

Σ : the input set

Γ : a stack symbol which can be pushed and popped from the stack

q_0 : the initial state

Z_0 : a start symbol which is in Γ .

F : a set of final states

δ : mapping function which is used for moving from current state to next state.

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Transition function δ takes as argument a triple

$\delta(q, a, x)$ where

q is a state in Q

a is either an input symbol in Σ or a can be ϵ

x is stack symbol, that is a member of Γ

The output of δ is finite set of pairs (p, γ)

p – new state

γ – string of stack symbols that replaces x at the top of the stack

If $\gamma = \epsilon$ then the stack is popped

If $\gamma = x$ then the stack is unchanged

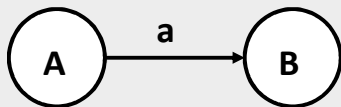
If $\gamma = yz$ then x is replaced by z and y is pushed on to the stack

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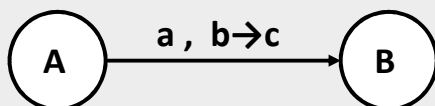
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GRAPHICAL NOTATION OF PDA

Finite Automata (Finite State Machine)



Push Down Automata (PDA)



PDA

a – Input symbol (This can also be ϵ)

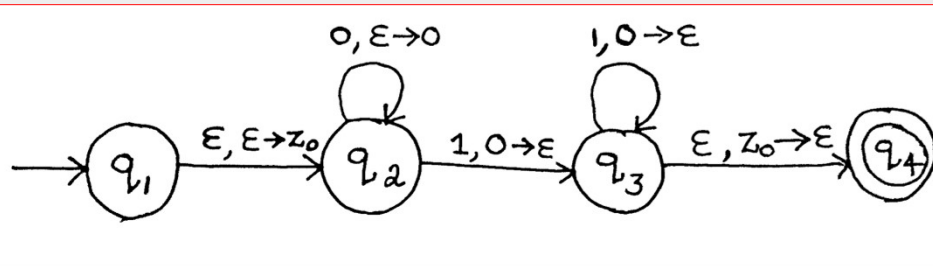
b – Symbol on top of stack. This symbol is popped (ϵ means the stack is neither read nor popped)

c – This symbol is pushed on to the stack (ϵ means nothing is pushed)

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Eg: Construct a PDA that accepts $L = \{0^n 1^n \mid n \geq 0\}$



Suppose our input string is 0011

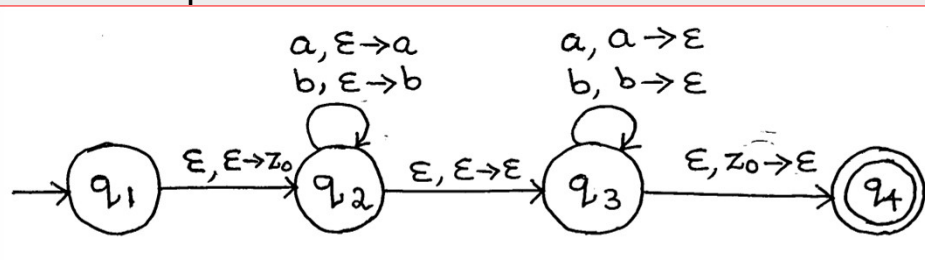
0
0
Z ₀

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Eg: Construct a PDA that accepts even palindrome of the form $L = \{ww^R \mid w = (a+b)^+\}$

Palindrome Example - 9889

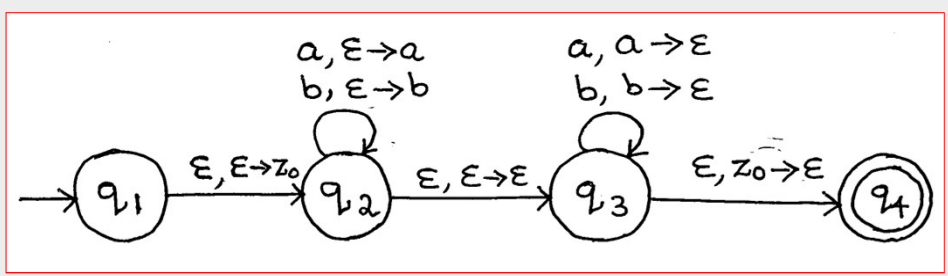


b
a
Z ₀

Consider the input strings (1) **abba**
(2) **abab**

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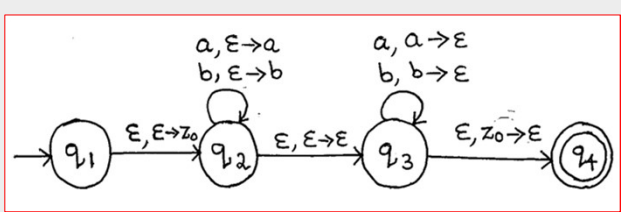


Consider the input strings **abba** .
 Assume that the ϵ is present after and before every symbol. Ie.,

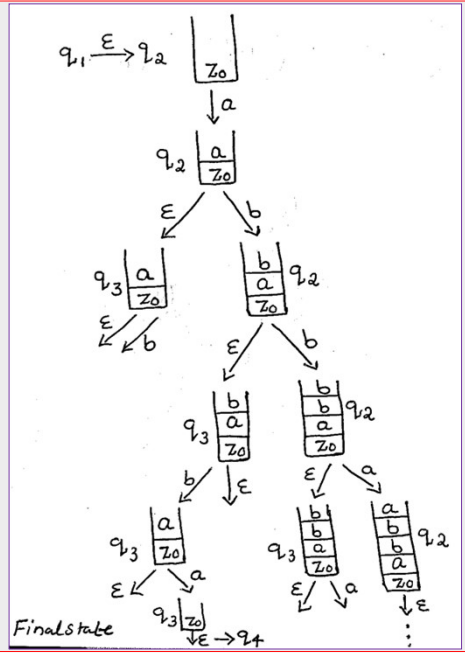
ϵ **a** ϵ **b** ϵ **b** ϵ **a** ϵ

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ϵ a ϵ b ϵ b ϵ a ϵ



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Instantaneous Description (ID) of PDA

➤ Instantaneous Description (ID) is an informal notation of how a PDA “computes” a input string and make a decision that string is accepted or rejected.

A ID is a triple (q, w, α) , where:

q is the current state.

w is the remaining input (unconsumed input)

α is the stack contents, top at the left.

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Turnstile notation

\vdash sign is called a “turnstile notation” and represents **one move**.

\vdash^* sign represents a sequence of moves.

Eg: $(p, b, T) \vdash (q, w, \alpha)$

This implies that while taking a transition from state p to state q , the input symbol ‘ b ’ is consumed, and the top of the stack ‘ T ’ is replaced by a new string ‘ α ’

δ is a transition function which maps $Q \times \{\Sigma \cup \epsilon\} \times \Gamma \rightarrow Q \times \Gamma^*$

- In a given state, PDA will read input symbol and stack symbol (top of the stack) and move to a new state and change the symbol of stack.

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Example : Define the pushdown automata for language $\{a^n b^n \mid n > 0\}$

Let $Q = \{q_0, q_1\}$

$\Sigma = \{a, b\}$

$\Gamma = \{A, Z_0\}$. Consider the input string aaabbb.

Row	State	Input	δ (transition function used)	Stack (Leftmost symbol represents top of stack)	State after move
1	q ₀	aaabbb		Z	q ₀
2	q ₀	a aaabbb	$\delta(q_0, a, Z) = \{(q_0, AZ)\}$	AZ	q ₀
3	q ₀	a aaabbb	$\delta(q_0, a, A) = \{(q_0, AA)\}$	AAZ	q ₀
4	q ₀	a aaabbb	$\delta(q_0, a, A) = \{(q_0, AA)\}$	AAAZ	q ₀
5	q ₀	aaab b	$\delta(q_0, b, A) = \{(q_1, \epsilon)\}$	AAZ	q ₁
6	q ₁	aaab b	$\delta(q_1, b, A) = \{(q_1, \epsilon)\}$	AZ	q ₁
7	q ₁	aaab b	$\delta(q_1, b, A) = \{(q_1, \epsilon)\}$	Z	q ₁
8	q ₁	ϵ	$\delta(q_1, \epsilon, Z) = \{(q_1, \epsilon)\}$	ϵ	q ₁

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- Initially, the state of automata is q₀ and symbol on stack is Z and the input is aaabbb as shown in row 1.
- On reading 'a' (shown in bold in row 2), the state will remain q₀ and it will push symbol A on stack.
- On next 'a' (shown in row 3), it will push another symbol A on stack. After reading 3 a's, the stack will be AAAZ with A on the top.
- After reading 'b' (as shown in row 5), it will pop A and move to state q₁ and stack will be AAZ.
- When all b's are read, the state will be q₁ and stack will be Z. In row 8, on input symbol ' ϵ ' and Z on stack, it will pop Z and stack will be empty. This type of acceptance is known as **acceptance by empty stack**.

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❖ Important points

- The above pushdown automaton is deterministic in nature because there is only one move from a state on an input symbol and stack symbol.
- The non-deterministic pushdown automata can have more than one move from a state on an input symbol and stack symbol.
- It is not always possible to convert non-deterministic pushdown automata to deterministic pushdown automata.
- The push down automata can either be implemented using **acceptance by empty stack** or **acceptance by final state** and one can be converted to another.

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CLOSURE PROPERTIES OF CFL

1. Union : If L_1 and L_2 are two context free languages, their union $L_1 \cup L_2$ will also be context free. For example,

- $L_1 = \{ a^n b^n c^m \mid m \geq 0 \text{ and } n \geq 0 \}$ and
- $L_2 = \{ a^n b^m c^m \mid n \geq 0 \text{ and } m \geq 0 \}$
- $L_3 = L_1 \cup L_2 = \{ a^n b^n c^m \cup a^n b^m c^m \mid n \geq 0, m \geq 0 \}$ is also context free.

➤ L_1 says number of a's should be equal to number of b's and L_2 says number of b's should be equal to number of c's. Their union says either of two conditions to be true. So it is also context free language.

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2. Concatenation : If L_1 and L_2 are two context free languages, their concatenation $L_1.L_2$ will also be context free. For example,

$$L_1 = \{ a^n b^n \mid n \geq 0 \} \text{ and } L_2 = \{ c^m d^m \mid m \geq 0 \}$$

$L_3 = L_1.L_2 = \{ a^n b^n c^m d^m \mid m \geq 0 \text{ and } n \geq 0 \}$ is also context free.

- L_1 says number of a's should be equal to number of b's and L_2 says number of c's should be equal to number of d's.
- Their concatenation says first number of a's should be equal to number of b's, then number of c's should be equal to number of d's.
- So, we can create a PDA which will first push for a's, pop for b's, push for c's then pop for d's. So it can be accepted by pushdown automata, hence context free.

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3. Kleene Closure : If L_1 is context free, its Kleene closure L_1^* will also be context free. For example,

$$L_1 = \{ a^n b^n \mid n \geq 0 \}$$

$L_1^* = \{ a^n b^n \mid n \geq 0 \}^*$ is also context free.

- So CFL are closed under Kleene Closure.

4. Intersection and complementation :

- If L_1 and L_2 are two context free languages, their intersection $L_1 \cap L_2$ need **not be context free**.
- Similarly, complementation of context free language L_1 which is $\Sigma^* - L_1$, need not be context free.
- So CFL are **not closed under Intersection and Complementation**.

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